

Electromigration Avoidance in Analog Circuits: Two Methodologies for Current-Driven Routing

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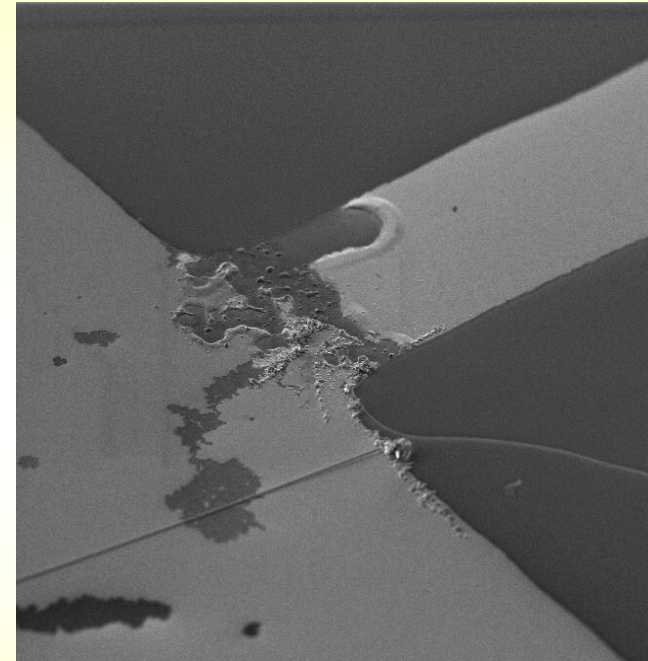
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Overview

- Motivation
- Design Flow
- Current Characterization
- Global Routing Method 1: Connection Graph, Steiner Tree
- Global Routing Method 2: Terminal Tree
- Method 1 + 2: Detailed Routing
- Experimental Results

Motivation

- Analog circuits for automotive applications
 - > high currents
 - > electromigration
- Until now, commercial analog layout tools do not consider current densities during routing of signal nets
- Hence, in-house development of current-driven routing tool is necessary as an “add on” to existing design system (Mentor Graphics)



Quelle: <http://ap.polyu.edu.hk/apavclo/public/gallery.htm>

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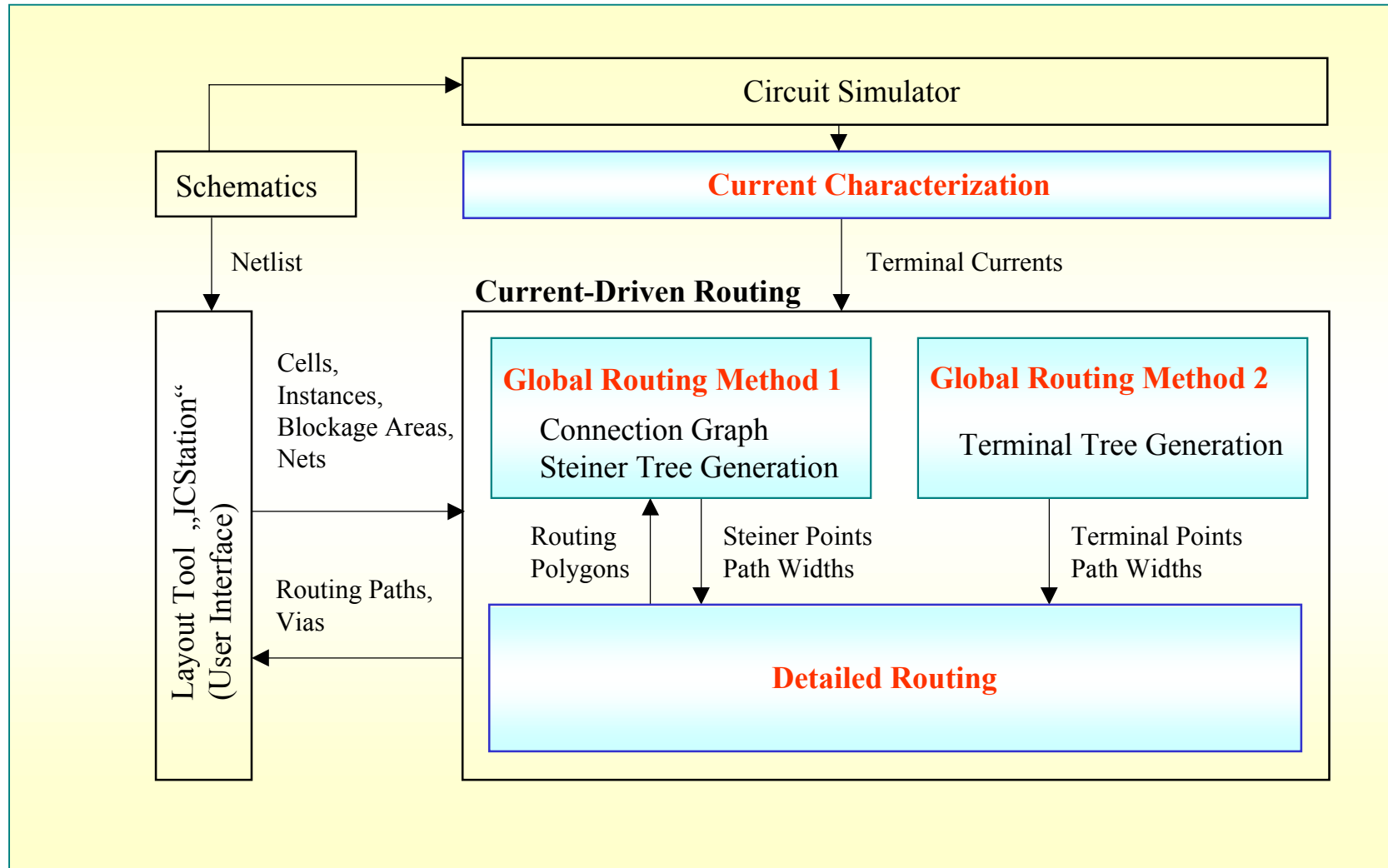
Definition “Current-Driven Routing”

Global
routing

- (1) Determination of the routing sequence of net segments
- (2) Calculation of the current in each net segment (Kirchhoff's current law)
- (3) Calculation of the wire width of each net segment
- (4) **Detailed routing** of the net segments in accordance with (1)

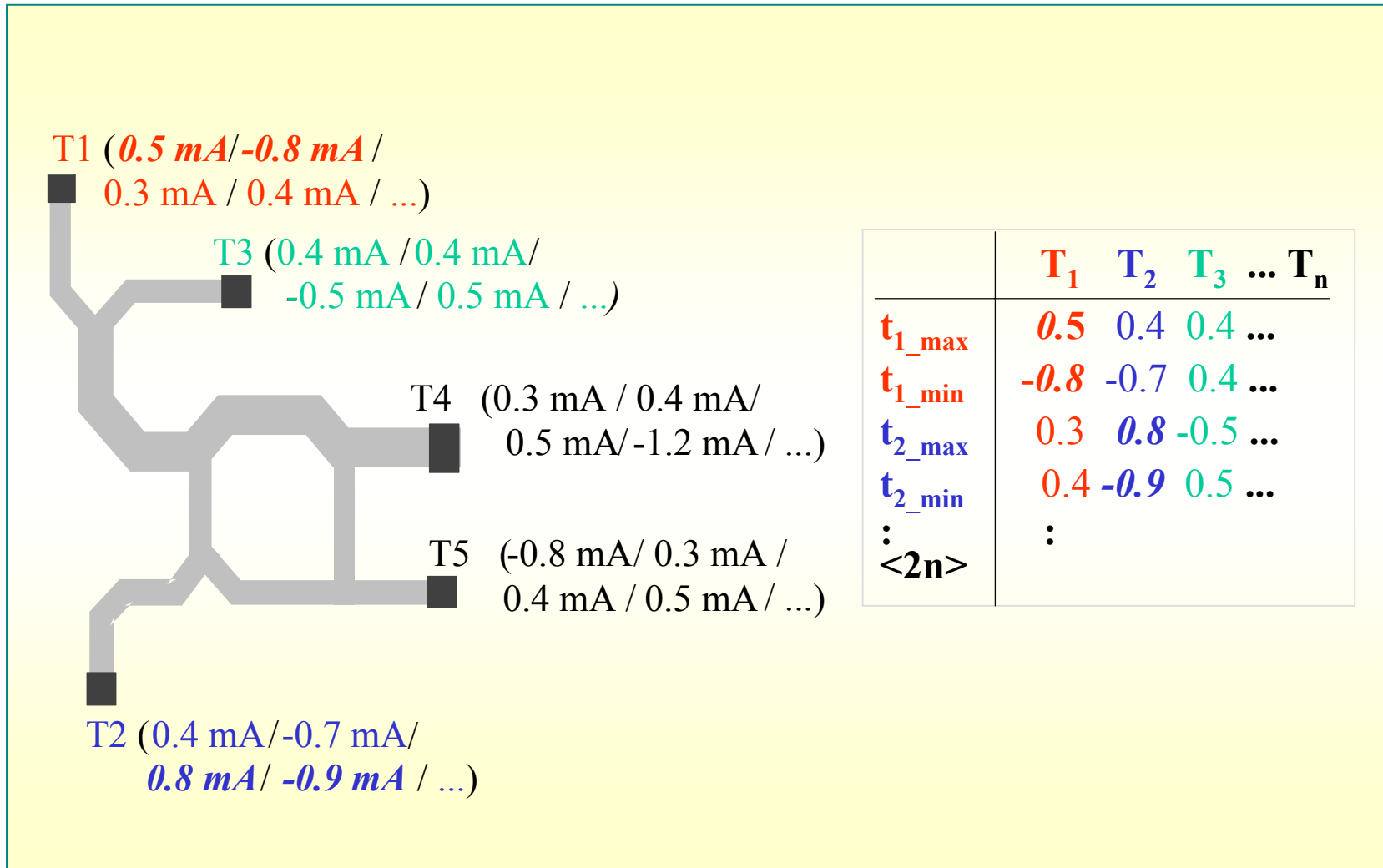
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Design Flow



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Current Characterization



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Wire Width Determination

$$w_{\min} = \max \left\{ \begin{array}{l} \frac{|I_{\max}| \cdot s}{J_{\text{peak_Layer}} \cdot d_{\text{Layer}}} \\ w_{\min_process} \end{array} \right.$$

s = safety factor ($s \approx 1.1 \dots 1.2$)

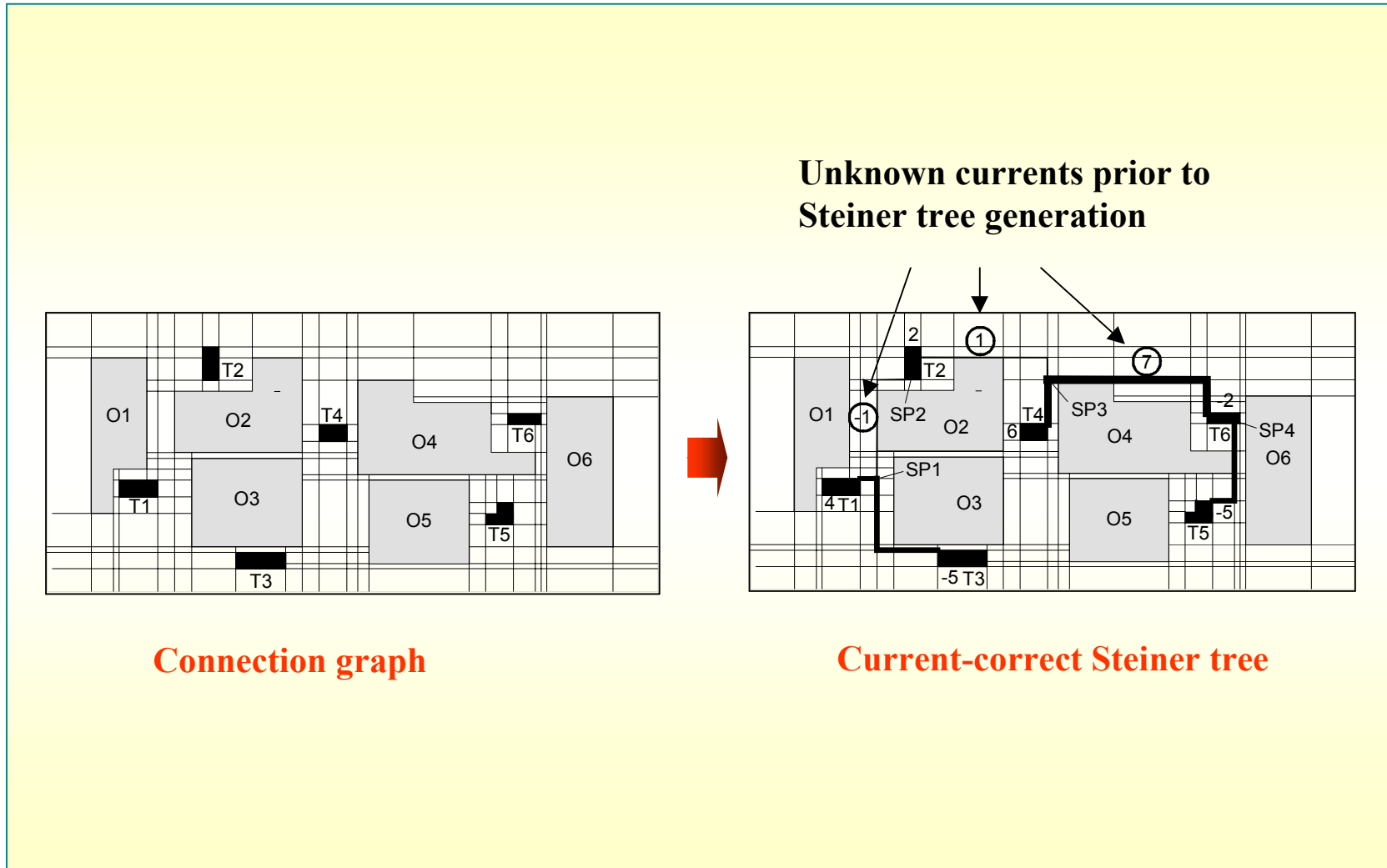
d_{Layer} = thickness of routing layer

I_{\max} = the maximum current on this path

$J_{\text{peak_Layer}}$ = layer dependent peak current density (process dependent)

$w_{\min_process}$ = minimum wire width determined by manufacturing process

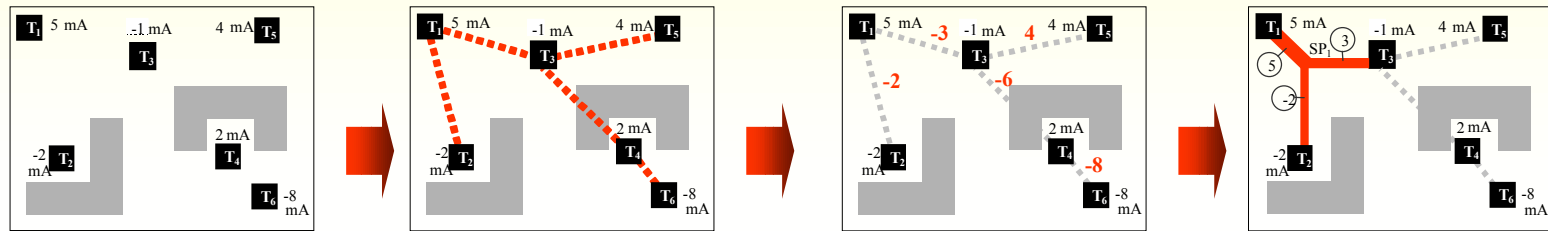
Global Routing Method 1: Steiner Tree



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Global Routing Method 2: Terminal Tree

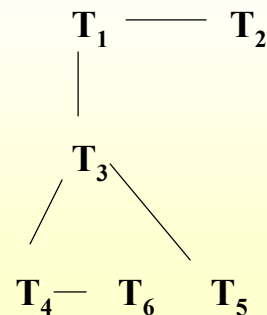
Given:
Terminal topology with current vectors,
terminals labeled in increasing x-order



(1) Left to right,
beginning with T2:
Find closest terminal
among previously
considered terminals:

$T_2 \rightarrow T_1$, $T_3 \rightarrow T_1$,
 $T_4 \rightarrow T_3$, $T_5 \rightarrow T_3$,
 $T_6 \rightarrow T_4$

(2) Derive **terminal tree**:



(3) **Calculate currents I**
of branches
(from leaves inbound)

$I(T_6-T_4) = -8\text{mA}$
 $I(T_4-T_3) = -6\text{mA}$
:
:
 $I(T_1-T_2) = -2\text{mA}$

(4) Forward terminal
connections and
calculated wire widths
to **detailed router**

Experimental Results

Circuits	Cells	Terminal-to-terminal connections (Flylines)	Nets
analog1	90	116	68
analog3	132	220	96
analog5	380	370	174

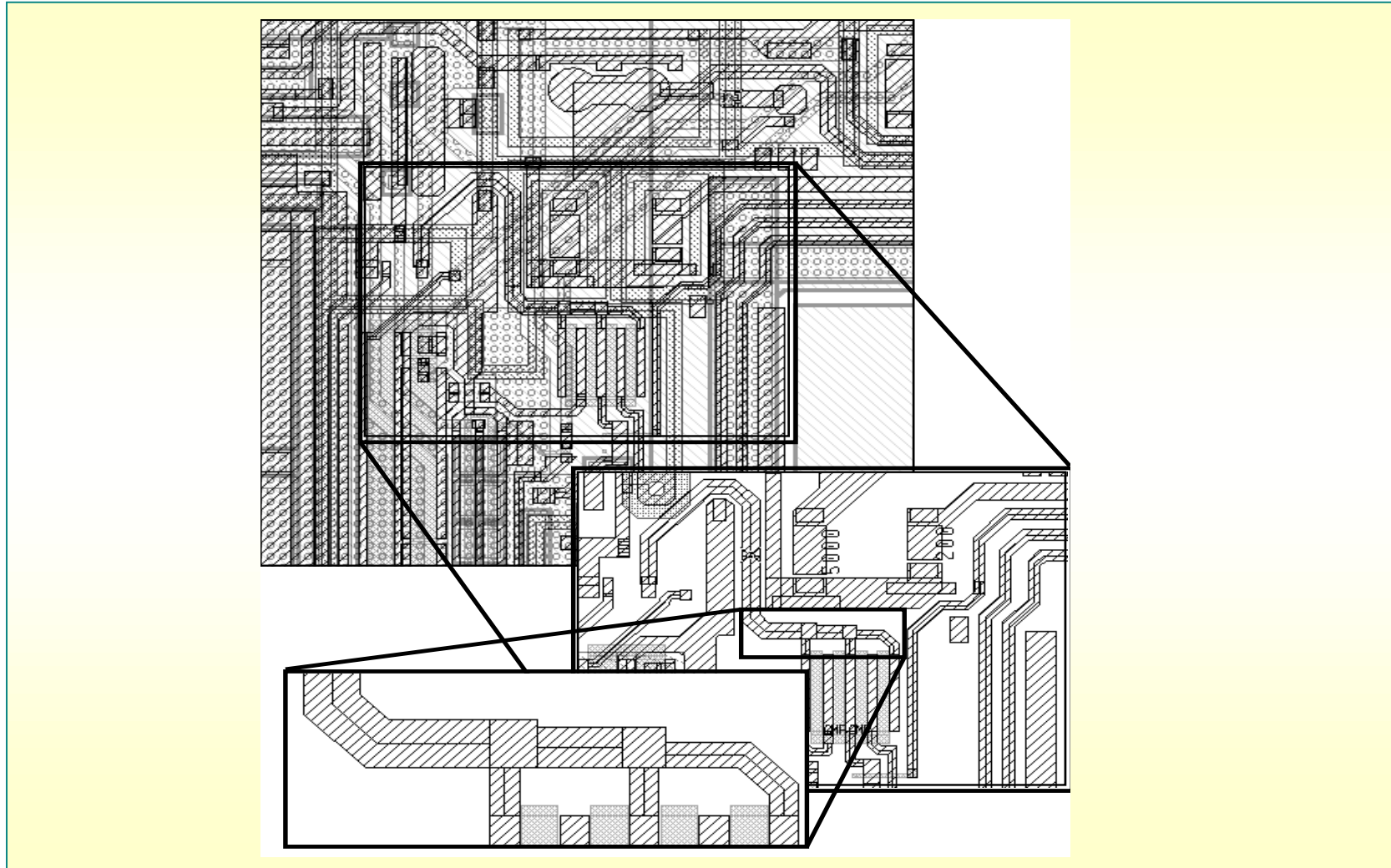
Circuits	Method	Steiner Points	Routing lengths (μm)	Vias	Area Reduction (vs. Manual Routing)
analog1	Steiner tree	48	24342	142	-0.4 %
	Terminal tree	14	23921	138	0.0 %
analog3	Steiner tree	116	37201	266	-0.3 %
	Terminal tree	27	36403	252	-0.1 %
analog5	Steiner tree	234	45585	458	-1.1 %
	Terminal tree	44	45548	456	-0.9 %

⇒ Routing quality is similar between both approaches, however:

- Terminal-tree-based approach is easier to implement
- Steiner-tree-based approach has problems with large complexities

⇒ Run times are only a fraction of manual current-correct routing time

Experimental Results (cont.'d)



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Summary

- Fast, yet sufficiently exact **current characterization** method based on current vectors
- Two **global routing methodologies** which calculate all branch currents *prior* to detailed routing, with the terminal-tree-based approach being the superior approach
- Efficient **detailed routing** which considers all constraints of current driven routing, especially varying wire widths
- **Verification** of our methodologies on “real world” analog circuits